

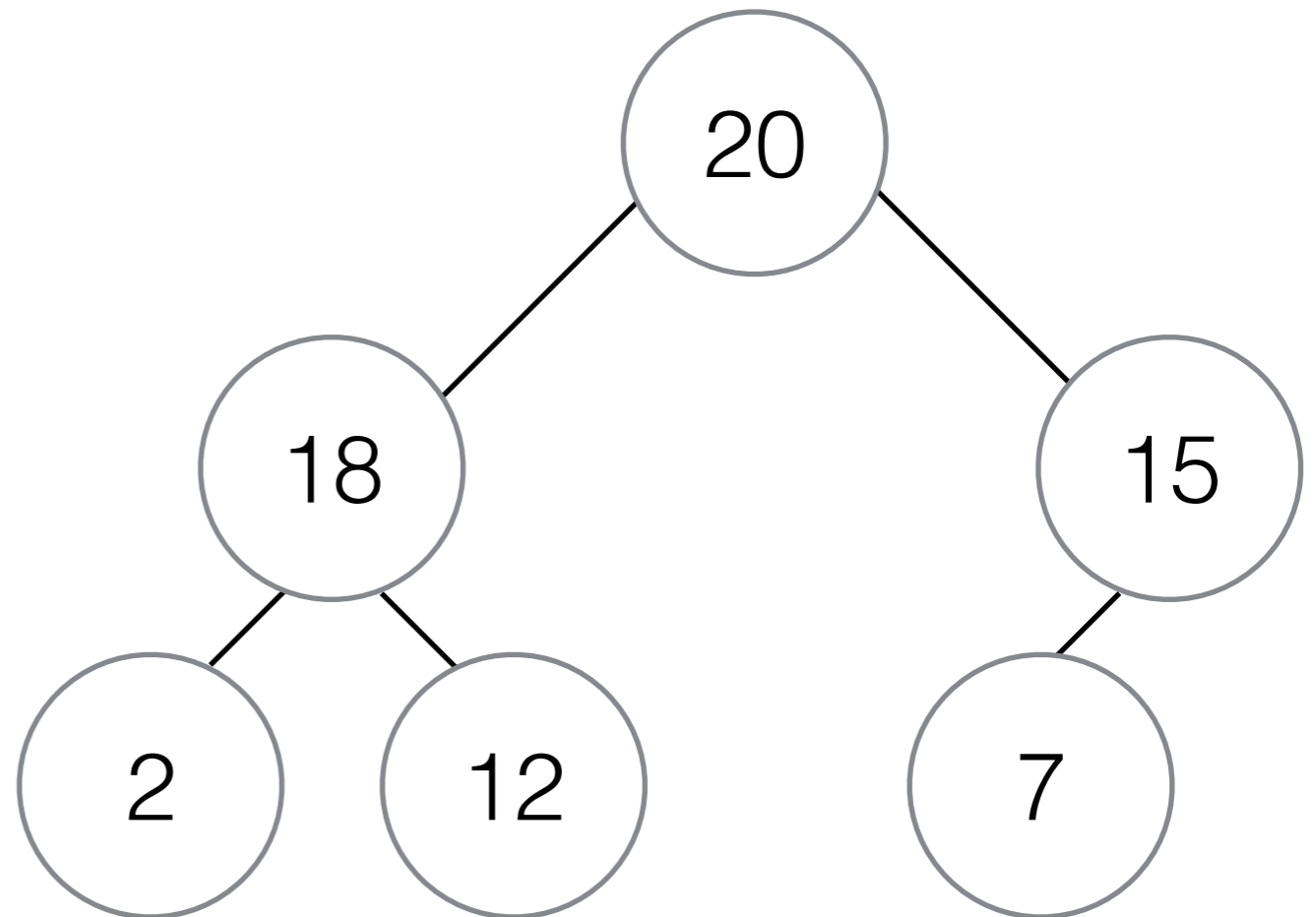
Heaps

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Heaps

(not to be confused with *the* heap memory)

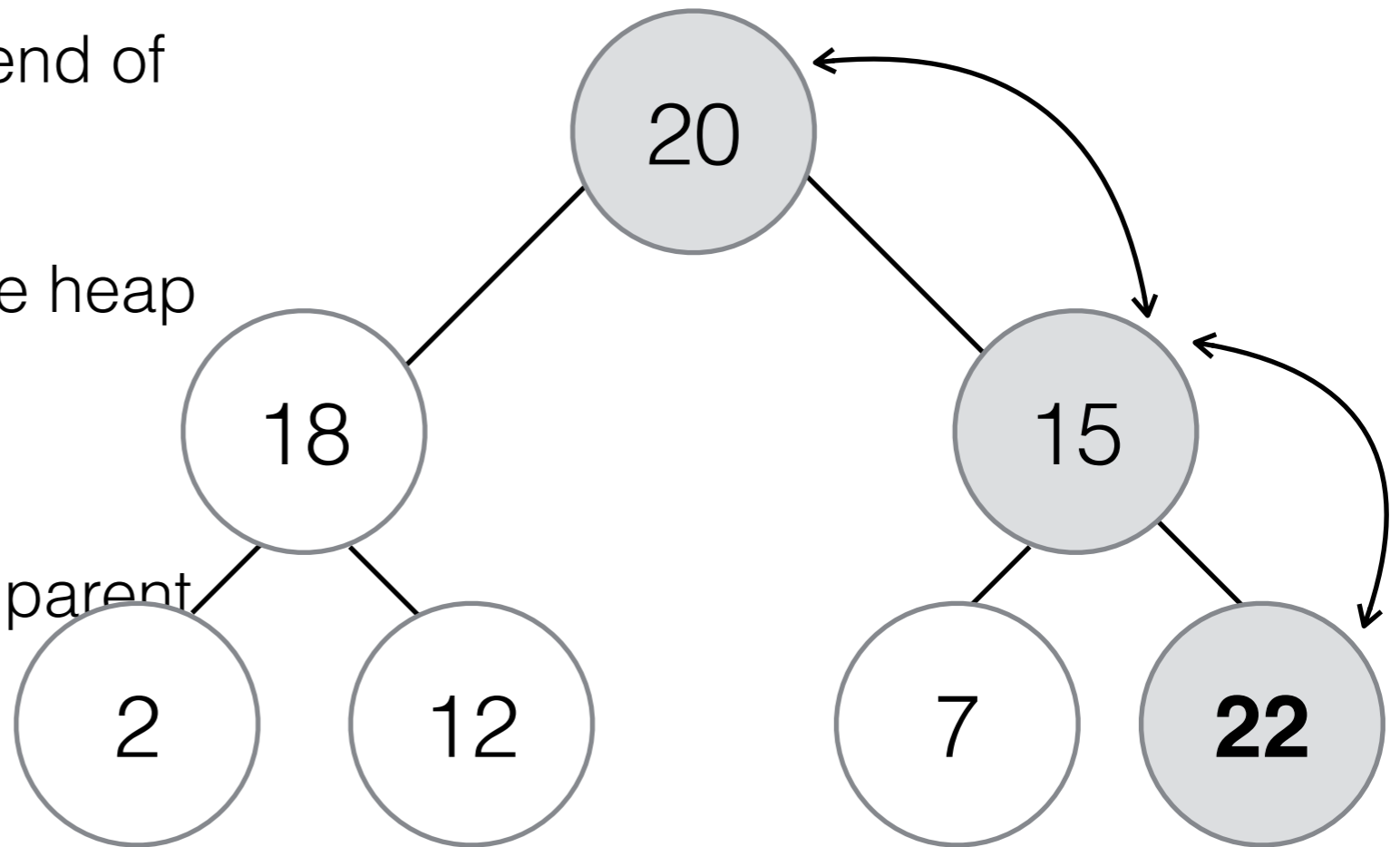
- **Binary tree**
(not necessarily a BST)
- value at node \geq value of children
- tree is perfectly **balanced**
- leaves are all 'as **left as possible**'
- heap is easily stored in an array
 - work from top to bottom, left to right



20	18	15	2	12	7
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Heaps

- To add to heap - add to end of array
- but tree may no longer be heap
- to-rebalance tree
 - compare new value to parent
 - swap if bigger
 - repeat until no swap or at root
- swap array values



20 18 15 2 12 7 **22**

22 18 **20** 2 12 7 **15**

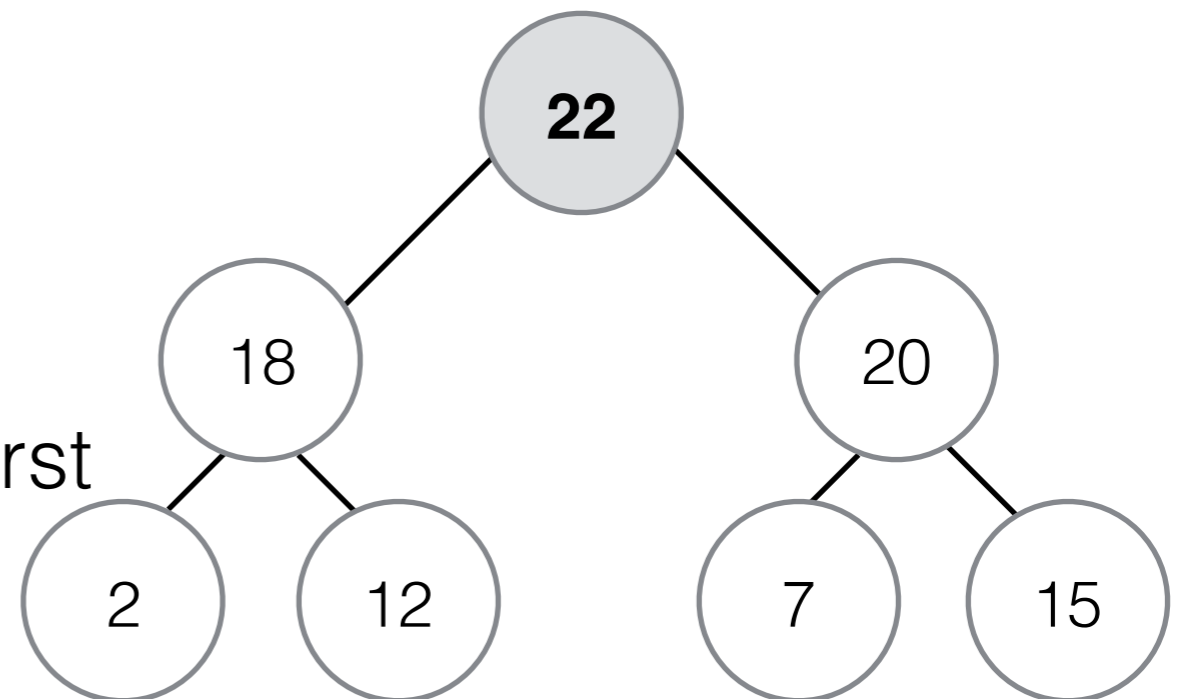
Heap Array Rules

- for any $i < n/2$
 - $\text{heap}[i] \geq \text{heap}[2 * i + 1]$
 - $\text{heap}[i] \geq \text{heap}[2 * i + 2]$

```
heap[heap_len] = new_value;
heap_len++;
child = heap_len - 1;
parent = (child - 1) / 2;
while ( child != 0 ) {
    if ( heap[parent] >=
        heap[child] ) {
        break;
    }
    swap ( heap[parent],
           heap[child] );
    child = parent;
    parent = ( child-1 ) / 2;
}
```

Heap as a Priority Queue

- item is added to queue
- value is the priority
- highest priority items taken first
- i.e. root downwards



- to remove root from queue -



- copy last element into [0]
- decrement queue length counter

Removing Root

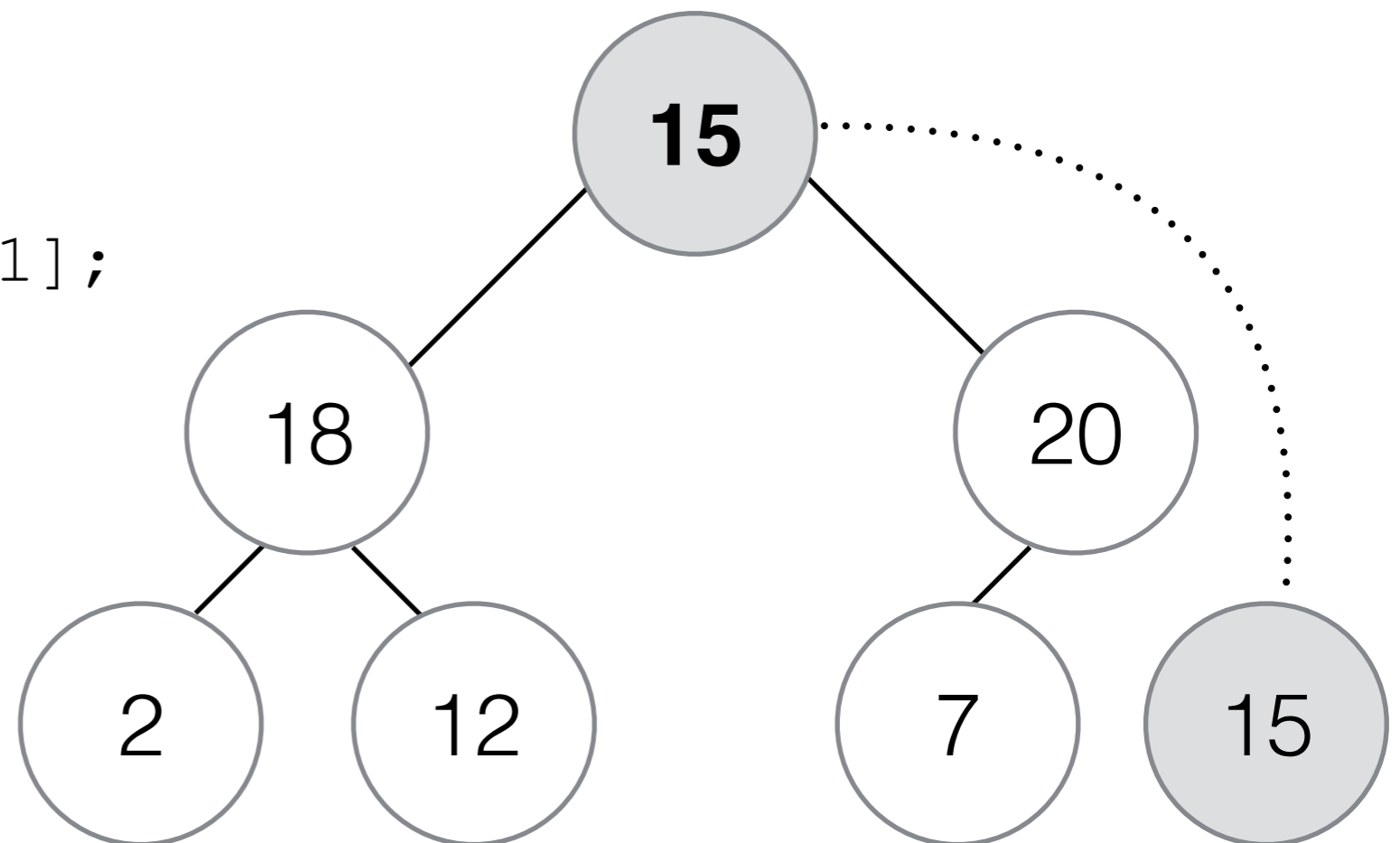
- `result = heap[0];`
`heap[0] =`
 `heap[heap_len - 1];`
`heap_len--;`

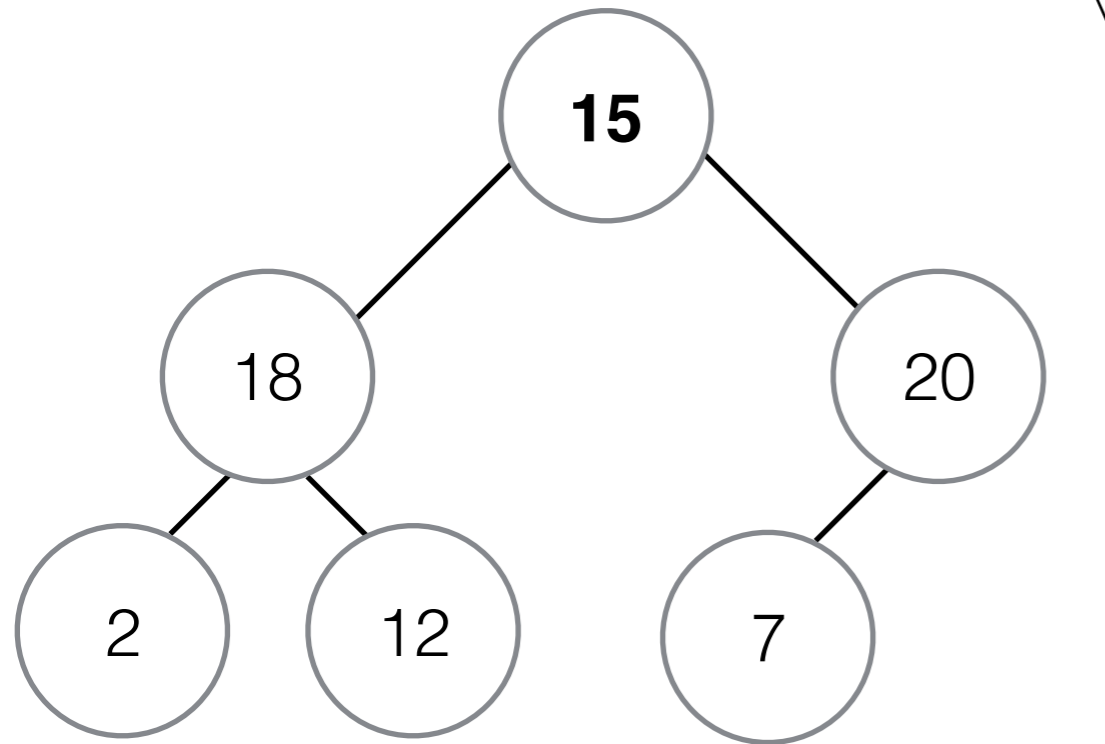
- Queue is no longer balanced

- work down from root

- if any child is greater than root

- swap





15 18 20 2 15 7

step-through

```

void movedown( int first ) {
    int parent = first;
    int max_child = 2 * parent + 1;

    while( max_child < heap_len ) {
        //i has 2 children
        if( max_child < heap_len - 1) {
            //right child is bigger
            if( heap[max_child] <
                heap[max_child + 1] ) {
                max_child++;
            }
        }
        if( heap[parent] >=
            heap[max_child]) {
            break;
        }
        swap( heap[parent],
            heap[max_child] );
        parent = max_child;
        max_child = 2 * parent - 1;
    }
}
  
```

Heapsort

- The heap was created for Heapsort by J.W.J. Williams (1964).
 - Build a heap
 - Algorithm removes biggest value from heap
 - add to end of new list/array
 - update heap to maintain balance
 - when heap is empty -> sorted array

Binary Heaps

- **Space** $O(n)$. $O(1)$ aux. space used in Heapsort.
- **Search** $O(n)$
- **Insert** $O(1)$ average, $O(\log n)$ worst
- **Delete** $O(\log n)$ average, $O(\log n)$ worst
- **Heapsort** $O(n)$ best, $O(n \log n)$ average, $O(n \log n)$ worst
- Worse cache performance than merge-sort - **why?**
- Not a **stable** sort
- Hard to parallelise
- Better worst-case time complexity than quicksort